

Technical data sheet

227PM-024-15-MB

Rotary actuator for pressure control

Description

Rotary actuator for adjusting air dampers for pressure control in HVAC installations

- Running time 150 s / 90°
- Torque 15 Nm
- Nominal voltage 24 VAC/DC
- Control (0)2...10 VDC
- Sensor 300 Pa (dynamic)
- Damper size up to approx. 3 m²
- Communication Modbus RTU
- Shaft coupling clamp
◇ 8-15 mm / Ø 8-20 mm



Technical data

Electrical data

Nominal voltage	24 VAC/DC
Nominal voltage range	19...29 VAC/DC
Power consumption motor (motion)	3,0 W
Power consumption standby (end position)	2,0 W
Wire sizing	5,5 VA
Control	Modbus RTU analog / (0)2...10 VDC
Feedback signal	Modbus RTU / analog (0)2...10 VDC, max. 0,5 mA
Priority control	closed / Pmin / Pmax / open
Connection motor	cable 1000 mm, 6 x 0,75 mm ² (halogen free)

Modbus

Protocol	Modbus RTU
Medium	RS-485, not electrically isolated
Number of nodes	max. 128
Baud rates	1200 / 2400 / 4800 / 9600 / 19200 / 38400 Bd
Byte sequence	MSB / LSB
Byte format	1 start bit, 8 data bits, 2 stop bits, none parity 1 start bit, 8 data bits, 1 stop bit, even parity 1 start bit, 8 data bits, 1 stop bit, odd parity
Termination	external (120 Ω)
Response time	≤ 10 ms + delay
Standard parameter	19200 Bd 1 start bit, 8 data bits, 1 stop bit, even parity delay 0 ms

Sensor

Calibration	300 Pa, height adjustment necessary (300 Pa = 1,2 in H ₂ O), dynamic measurement principle
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Technical data

Sensor

Measuring range	0...300 Pa
Burst pressure	1 bar
Nominal value	Pmin / Pmax / Pconst based on Pnom
Media	air 0...70°C / 5...95% r.H., non condensing
Mounting position	independent of position
Connection	Ultram 2200 / tube clip Ø 4-6 mm

Functional data

Torque	> 15 Nm
Damper size	up to approx. 3 m²
Synchronised speed	±5%
Direction of rotation	adjustable
Manual override	gearing latch disengaged with pushbutton, self-resetting
Angle of rotation	0°...max. 95° can be limited with adjustable mechanical end stops
Running time	< 150 s / 90° (adjustable 70...420 s / 90°)
Sound power level	< 35 dB(A)
Shaft coupling	clamp ◇ 8-15 mm / Ø 8-20 mm
Position indication	mechanical with pointer
Service life	> 60'000 cycles (0° - 95° - 0°)

Safety

Protection class	III (safety extra-low voltage)
Degree of protection	IP 42
EMC	CE (2014/30/EU)
LVD	CE (2014/35/EU)
RoHS	CE (2011/65/EU)
Mode of operation	Typ 1 (EN 60730-1)
Rated impulse voltage	0,8 kV (EN 60730-1)
Control pollution degree	3 (EN 60730-1)
Ambient temperature normal operation	0°C...+50°C
Storage temperature	-20°C...+80°C
Ambient humidity	5...95% r.H., non condensing (EN 60730-1)
Maintenance	maintenance free

Dimensions / Weight

Dimensions	115 x 65 x 66 mm
Weight	435 g

Operating mode / Properties

Operating mode

Through connecting the power supply to BU+BN (1+2) and a reference signal Y to BK (3) in the range of (0)2...10 VDC, the actuator regulates to the specified set point. The current pressure in % of Pnom is provided as a feedback signal U on GY (4) for other actuators.

CAP modes / override controls:
 -AC*/DC signal to terminal BK (3)
 -Modbus RTU WH (5,6)

The actuator is overload-proof, requires no limit switches and automatically stops when the end stop is reached.

Direct mounting

Simple direct mounting on the damper shaft with a clamp, supplied with an anti-rotation strap to prevent the actuator from rotating.

Manual override

Manual override is possible with the self-resetting pushbutton (the gearing latch remains disengaged as long as the pushbutton is pressed).

Edit

The selector allows the changing of values. The position of the arrow shows the value set. The changes are displayed as soon as the selector is moved $\pm 10^\circ$ from the position.

Pres / Unit

Setting the desired actual pressure unit to Pa and H₂O.

Pmin

Adjust the desired pressure Pmin (setpoint Y = 0 / 2 VDC).

Pmax

Adjust the desired pressure Pmax (setpoint Y = 10 VDC).

Diag

Diagnostic menu:
 off - diagnostic mode is off
 on - diagnostic mode is on, motor off
 oP - opens the damper
 cL - closes the damper
 Lo - activated Pmin
 Hi - activated Pmax
 Adp - adaption drive
 123 - software version

Mode

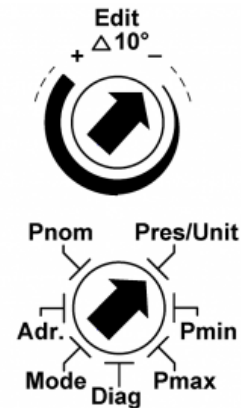
Setting the direction of rotation:
 0-n...0-10 VDC normal
 2-n...2-10 VDC normal
 0-i ...0-10 VDC invers
 2-i ...2-10 VDC invers

Adr

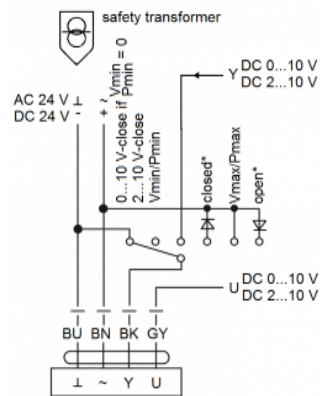
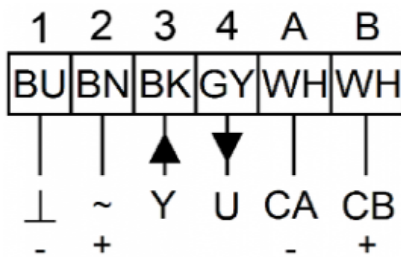
Setting the address of the Modbus (1...247).

Pnom

Setting the nominal pressure depending on the VAP-box.



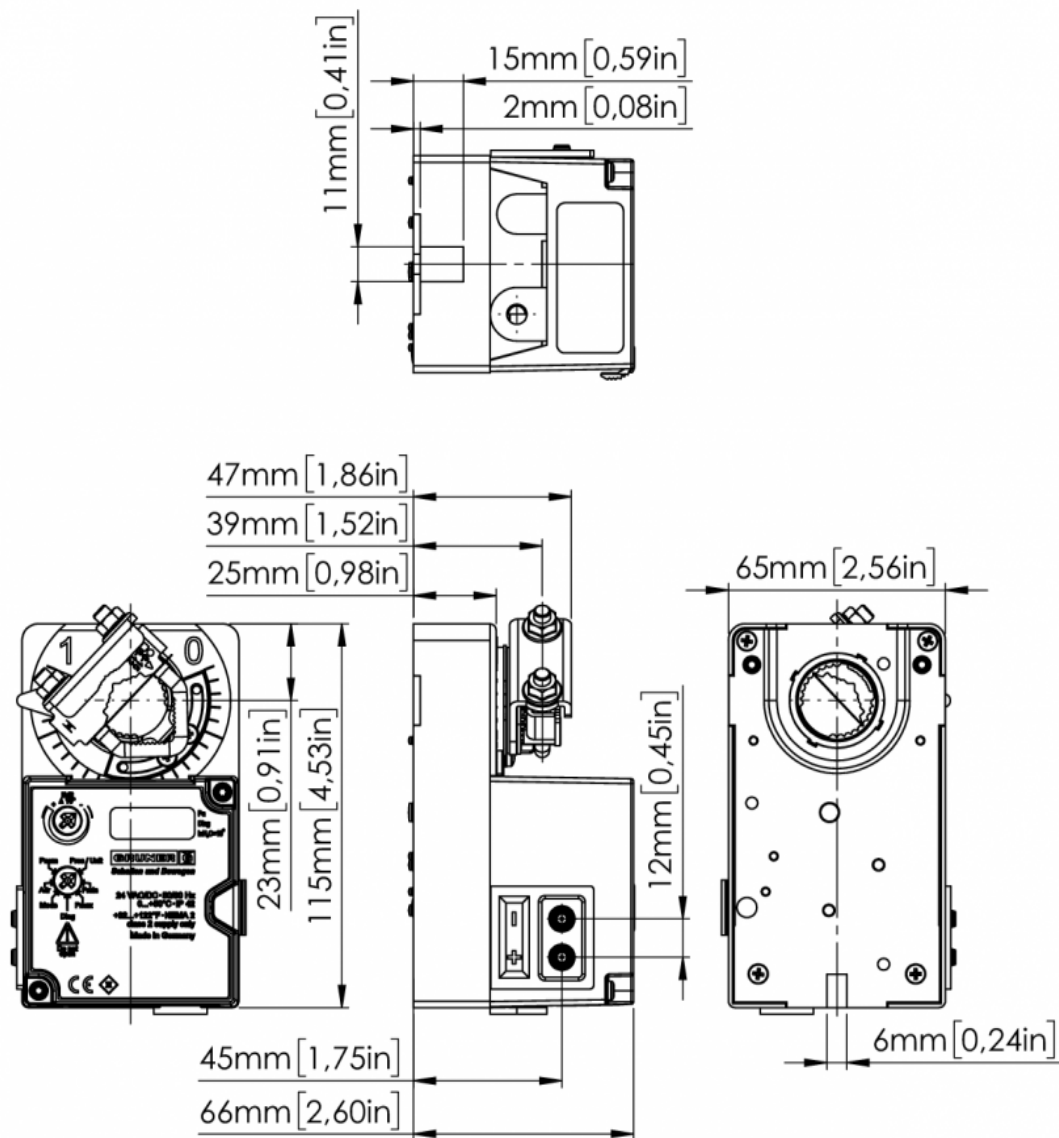
Connection / Safety remarks



Safety remarks

- Connect via safety isolation transformer!
- The device is not allowed to be used outside the specified field of application, especially in airplanes.
- It may only be installed by suitably trained personnel. Any legal regulations or regulations issued by authorities must be observed during assembly.
- The device may only be opened at the manufacturer's site.
- The device is not allowed to be disposed of as household refuse. All locally valid regulations and requirements must be observed.
- When calculating the required torque, the specifications supplied by the damper manufacturer's (cross-section, design, installation site), and the air flow conditions must be observed.

Technical drawing



Modbus register

No.	Register	Memory
0	Set point 0...100.00 [%]	RAM
1	Override control	RAM
2	Command	RAM
3	Actuator type	EEPROM
4	Relative position 0...100.00 [%]	RAM
5	Absolute position 0...650.00 [°][mm]	RAM
6	Relative value 0...100.00 [%]	RAM
7	Absolute value 0...65535 [m³/h][l/s][pa]	RAM
10	Feedback signal 0...10000 [mV]	RAM
103	Software version	EEPROM
105	Min. value 0...100.00 [%]	EEPROM
106	Max. value 0...100.00 [%]	EEPROM
108	Bus fail position	EEPROM
109	Timeout 0...65535 [s]	EEPROM
120	Min. value 0...65535 [m³/h][l/s][pa]	EEPROM
121	Max. value 0...65535 [m³/h][l/s][pa]	EEPROM
122	Interface mode	EEPROM
130	Address 1 - 247	EEPROM
200	Nominal value 0...300.00 [Pa]	EEPROM
201	Unit	EEPROM
551	Mode	EEPROM
568	Modbus settings	EEPROM
569	Modbus response time	EEPROM

- Registers in bold can be written / Register in Fettschrift sind schreibbar
- RAM registers are non-permanent / RAM Register flüchtig
- EEPROM registers are permanent (max. 1 Mio. write cycles)
- EEPROM Register nicht flüchtig (max. 1 Mio. Schreibzyklen)

Register 1:

Override control	
0	-
1	Open
2	Close
3	Min
4	Max

Register 2:

Command	
0	-
1	Adaption
2	-
3	-
4	Controller reset

Modbus register

Register 3:

Actuator type	
0	No actuator
1	HVAC / water actuator
2	VAV actuator
3	Fire protection actuator
4	GUAC VAV
5	GUAC CM
6	GT

Register 108:

Bus fail position*		
0	-	
1	Close by bus timeout	timeout >120s (default setting / Werkseinstellung)
2	Open by bus timeout	
3	Vmin by bus timeout	
4	Vbet by bus timeout	
5	Vmax by bus timeout	

*retriggered by any read/write command to actuator's address

*wird durch jegliches lesen/schreiben auf die entsprechende Antriebsadresse zurückgesetzt

Register 122:

Interface mode		
Value	Signal input	Feedback signal
0	Analog (0)2...10 V	(0)2...10 V
1	Modbus via Register 0	(0)2...10 V
2	Modbus via Register 0	Register 10
3	Analog (0)2...10 V	Register 10

Register 201:

Unit	
0	[l/s]
1	[m³/h]
2	[Pa]
3	[in H ₂ O]
4	[°]
5	[mm]

Register 551:

Mode	
Bit	Function
0	1 = 2-10V
1	1 = Override control Modbus
2	1 = Override control close
3	1 = Override control open
4	1 = Override control Vbet
5	1 = Override control Vmax
6	1 = option reversal activ (Drehrichtungsänderung)
7	1 = Motor off
8	1 = Override control Vmin

Modbus register

Register 568:

Modbus parameter				
Display	Value	Baudrate	Parity	Stop bits
1	0	1200	none	2
2	1	1200	even	1
3	2	1200	odd	1
4	3	2400	none	2
5	4	2400	even	1
6	5	2400	odd	1
7	6	4800	none	2
8	7	4800	even	1
9	8	4800	odd	1
10	9	9600	none	2
11	10	9600	even	1
12	11	9600	odd	1
13	12	19200	none	2
14¹⁾	13	19200	even	1
15	14	19200	odd	1
16	15	38400	none	2
17	16	38400	even	1
18	17	38400	odd	1
19 ²⁾	18	1200	none	1
20 ²⁾	19	2400	none	1
21 ²⁾	10	4800	none	1
22 ²⁾	21	9600	none	1
23 ²⁾	22	19200	none	1
24 ²⁾	23	38400	none	1

1) default setting / Werkseinstellung

2) not Modbus standard, only Gruner / kein Modbus Standard, nur Gruner

Register 569: Repsonse time: 10 ms + "delay"**"Delay": 3 ms x 0...255**